



SPECS

- **Automatic, Semi- automatic, or Manual Workstations**
- **Lanco HLF 2002- S Linear Transfer System**
- **Vision-guided Robotics**
- **Robotic Workcells**
- **High Speed Indexer**
- **Lean Cell**
- **Rotary Tables**
- **Well- controlled Pressing or Welding Processes**
- **Test Systems**
- **Custom Machines**

Subject: automation for electronic industry



ABOUT THIS PROJECT

Sequence of Operations:

- 1: De-stack full trays and convey them to the robot unload station.
- 2: Empty trays are then conveyed from the unload position to the tray removal station.
- 3: Robotic Picks Bushings & Header from feeding mechanisms.
- 4: Robotic load to mold press.
- 5: Remove from mold press.
- 6: Cool & load to final Tray.
- 7: Headers are checked and if they pass, are returned to the pallet.
- 8: Headers that fail the test are dropped into the reject chute.